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<input type="checkbox"/>	L9	4553899.pn.	2
<input type="checkbox"/>	L8	4382743.pn.	2
<input type="checkbox"/>	L7	('20040210342' '20040105746' '20010051085' '6641355' '6558102' '5340187' '4706779' '4201511' '3915429' '3635636' 'EP 1384698A' 'EP 568758A')!.ABPN1, NRPN, PN, TBAN, WKU.	23
<input type="checkbox"/>	L6	rotating and L5	320
<input type="checkbox"/>	L5	rotat\$3 and L4	603
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<input type="checkbox"/>	L3	gantry robot and lift	73
<input type="checkbox"/>	L2	double lift	373
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L1 lift\$3 (truck or vehicle or robot) and telecop\$3 and load 3

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[◀ Back to Previous Page](#)**Results Key:****JNL** = Journal or Magazine **CNF** = Conference **STD** = Standard**1 Manipulator system for constructing overhead distribution lines**

Ohnishi, H.; Yokoyama, H.; Waki, S.; Mochizuki, K.; Toratani, T.; Eurukawa, H.; Mukai, F.; Yokoyama, S.; Kojima, H.; Kaihara, N.;

Robot and Human Communication, 1992. Proceedings., IEEE International Workshop on, 1-3 Sept. 1992

Pages:235 - 240

IEEE CNF**2 PLC control systems for the remote control of cranes and manipulators**

Hughes, S.;

Advances in Programmable Logic Controllers, IEE Colloquium on, 24 Feb 1992

Pages:5/1 - 5/4

IEE CNF